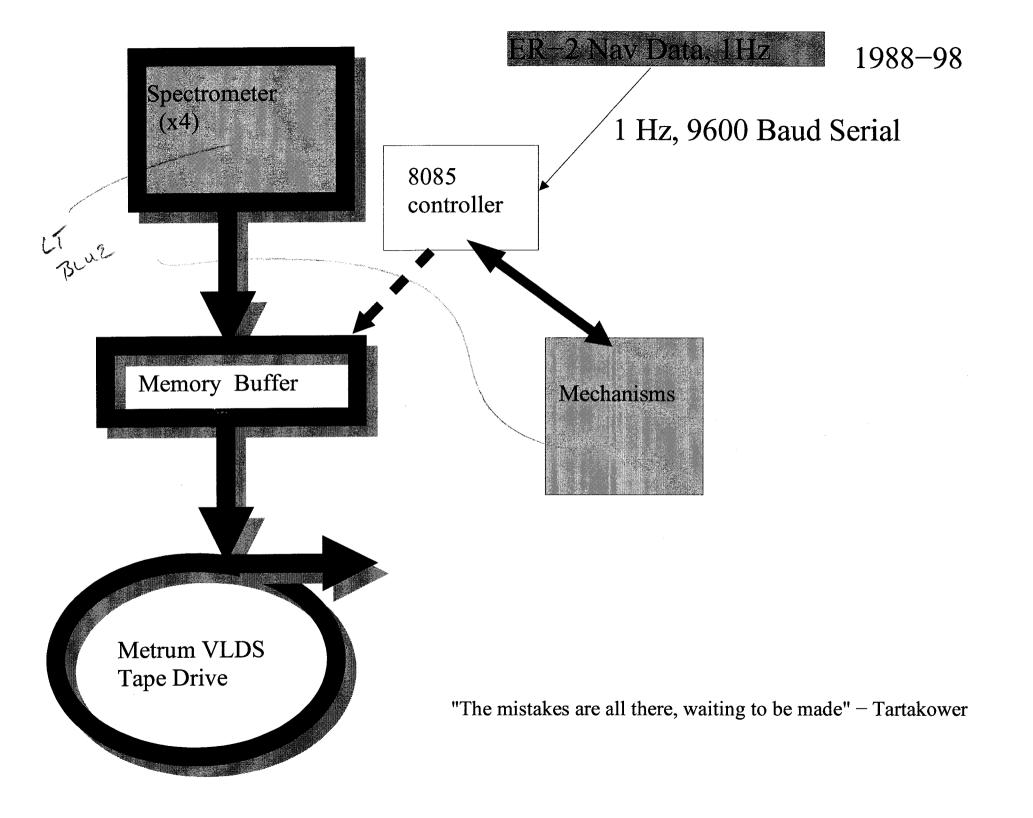
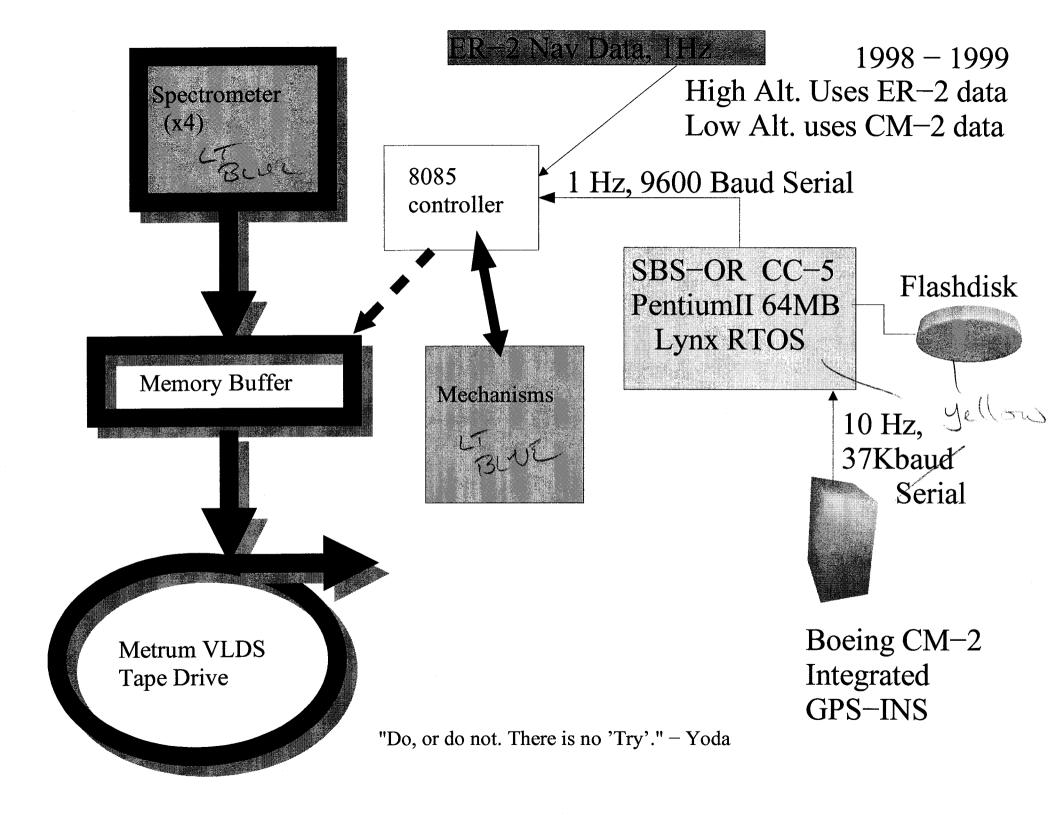
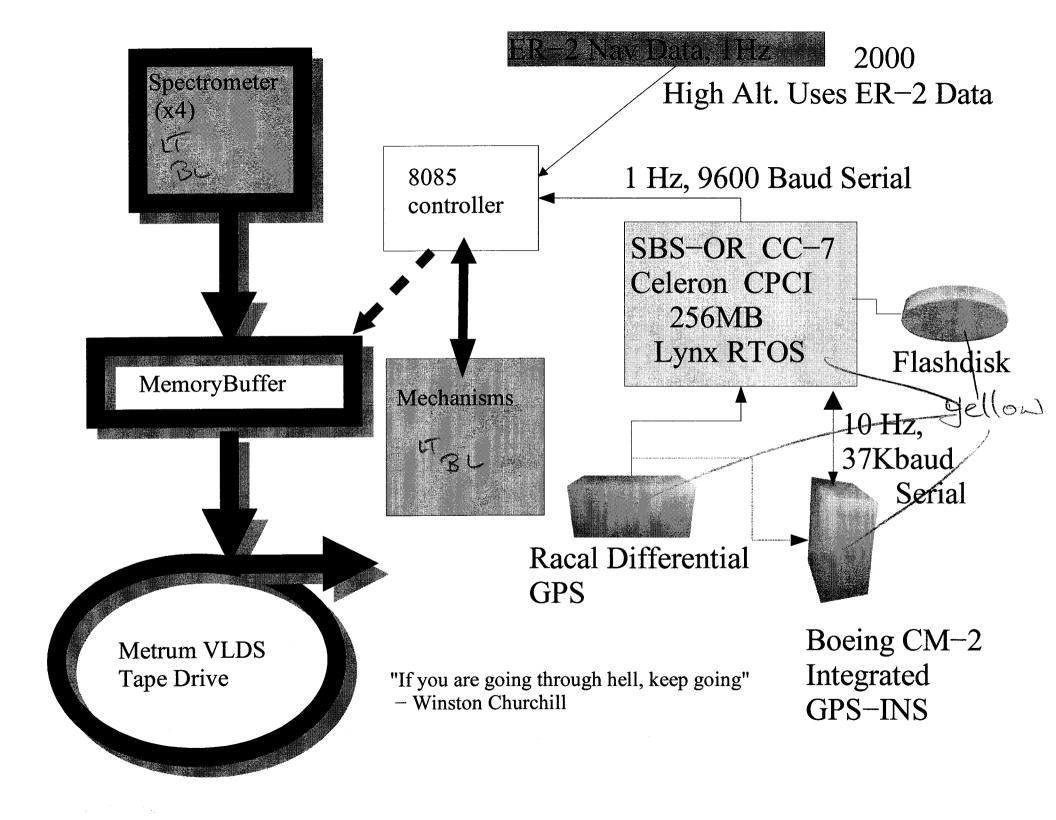
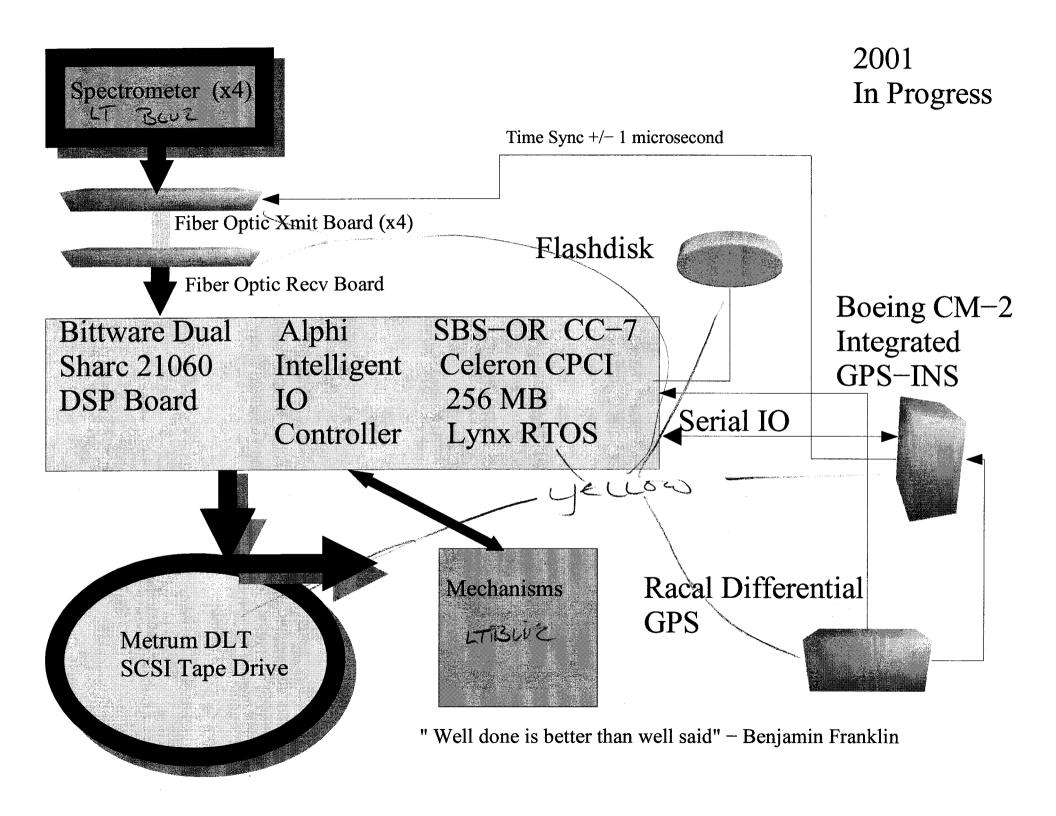
AVIRIS Instrument Computer Changes in Hardware and Software for Data Acquisition

"Too clever is dumb" - German Proverb









Points to Ponder

- You need an RTOS to implement a complex Real Time System.
- Don't write Assembly language unless you MUST. Be able to say "Let's change Hardware".
 A good RTOS lets you write portable code.
- The difference between Hardware and Software:
 - Hardware is what breaks when you #%*! with it long enough, Software is what works when you #%*! with it long enough.

Sources

- Operating Software lynuxworks.com, Lynx RTOS
 - Excellent Support at a reasonable price. POSIX standard.
- DSP bittware.com, dual Analog Devices "SHARC"
 - Outstanding support and assistance, "works as advertised"
 - New "Hammerhead" board offers 2.4 Gflops.
- Integrated GPS/INS systron.com (was Boeing)"CM-2"
 - Outstanding reliability "A brick that knows where it is"
 - Systron bought the Migits product from Boeing in December
- CPCI Computer sbs.com SBS/OR "CC-7"
 - Excellent Support and reliability.
- Digital IO alphitech.com Intelligent Digital IO board
 - On board TMS320 to handle mechanisms control

Additional Information

- The CM-2 gps/inertial nav system is still available but going fast at about \$22k/each. There is a CM-3 with 12 channel GPS coming.
- Initializing a CM-2 can be annoyingly difficult if you only know what is in the manual. I will make myself available for off—line discussions for anyone interested in how to make it work.
- Using a DSP for IO is the closest thing to magic that you can use. This programming can also be explained IFF you are interested.